# **CHS Level of Confidence Approach for SDB**

#### René Chénier, Khalid Omari and Mesha Sagram







Canada

#### **Canadian Hydrographic Service Regions**

- CHS is mandated to support safe navigation in Canadian waters
- Responsible for providing up-to-date, authoritative and standardized hydrospatial information

Canadian Arctic : 3.7 Million km<sup>2</sup> of water Atlantic Central Pacific Quebec The Oceans (Pacific, Arctic, and Atlantic), and internal waters, cover a surface area of 7.1 million km<sup>2</sup> Total coastline 243,700 km

2



#### **Current Paper Chart Coverage**



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# **Category Zone of Confidence (CATZOC)**

Only 14 % of the Arctic is considered as adequately surveyed	CATZOC	Survey Quality	Position Accuracy	Depth Accuracy
	A1	Modern	± 5 m + 5% depth	0-10 m: 0.6 m 10-30 m: 0.8 m
She attantes and	A2 & B	Adequate	± 20 m (A2) ± 50 m (B)	0-10 m: 1.2 m 10-30 m: 1.6 m
ELCANTING.	С	Insufficient	± 500 m	0-10 m: 2.5 m 10-30 m: 3.5 m
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Source: DFO-Science, CHS / MPO-Science, SHC chsinfo.XNCR@dfo-mpo.gc.se June / Juin 2017



# **Chart White Space**



Chart 5510 (Povungnituk, QC). White areas in Chart depicted above are unsurveyed.

Chart 5510 overlaid on RapidEye image (July 12, 2011).



#### **Proposed Low Impact Shipping Corridors**



#### **Canadian Space Agency (CSA) Funding**

- Government Related Initiatives Program (GRIP)
  - Extraction of accurate Coastline and Intertidal Zones
  - Satellite Derived Bathymetry (SDB)
  - $\circ\,$  Change Detection

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- Shipping Corridor Determination
- Data Integration in CHS Processes and Products

#### Data Utilization and Application Plan (DUAP)

- RCM Data Simulation
- $\,\circ\,$  Shorelines, Intertidal Zones and Tidal Height
- Charting and Surveying Priorities
- Synthetic Aperture Radar (SAR) Bathymetry

7

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# **Oceans Protection Plan**

- Multibeam and LiDAR surveys for priority and high risk areas across Canada
- Support for remote sensing projects







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# Study Site -Cambridge Bay

- The Canadian Arctic is where CHS has the most gaps in hydrographic surveys
- The study site is located in Cambridge Bay, Nunavut (69°07' N, 105°02' W)
- Cambridge Bay is a hamlet situated on Victoria Island









#### Dataset: Wordview-2 Stereo Pair

WorldView-2 stereo pair acquired on September 20, 2015 over Cambridge Bay









Survey Type	Year	Number of points
		( <b>0-20</b> m)
Multibeam	2017	599,305
Multibeam	2015	1,265,263
Multibeam	2014	1,284,582
Lidar	1992	1193
LiDAR	1985	8953
	Total	3,159,297



A- All survey points B- Survey points from 0-20 m



# **Geometric Processing- Physical model**

Mode	GCP	ICP	ICP RMS errors (m) X, Y,
U2	8	81	1.5, 1.4
U25	8	105	1.4, 1.5



•The accuracy of the Radarsat orbit: MDA guarantees 5 m with 90 % level of confidence.

The elevation ranges from 10 m to 1000 m









# **SDB Approaches Evaluated**

- Photogrammetric 3D manual approach
  - Digital photogrammetric software SOCET SET
- Photogrammetric Automatic approach
  - PCI Geomatica -Semi-Global Matching (SGM) algorithm
- Empirical approach
  - o Multi-band approach
- Classification
  - o Random forest





# **Approaches Evaluated**

#### **Classification :**

- A random forest decision tree classification was used
- Training areas were collected using the survey information
- Classes of depth of 0.5 m intervals were created using available survey points
- The random forest classification was applied to the multispectral bands (Red, Green, Blue, and Yellow)

#### Empirical - multi-band model (Lyzenga 1985)

- A Multi-band approach was selected , the multispectral bands used (Red, Green, Blue, and Yellow)
- 10% of the survey data were used for the creation of the model





## **Approaches Evaluated**

#### Photogrammetric approach:

- Geometric model was computed using the Rational Polynomial Coefficients (RPCs)
- Additional tie points (~1000) were collected in order to obtain better relative accuracy between the images

#### **Photogrammetry 3D Manual approach :**

- Photogrammetrist visually extracted the isobaths at 1 m interval
- Light and tidal correction were done with survey points as a reference to determine the appropriate water depth

#### Photogrammetry Automatic approach:

- PCI Geomatics -Semi-Global Matching (SGM) algorithm
- Light refraction and tidal correction was applied







# Results

# For total extracted coverage

Approach	Coverage 0-20 m
A- 3D Manual Photogrammetry	100 %
B- Classification Random Forest	81 %
C- Empirical Multiband	59 %
D- Automatic Photogrammetry	39 %

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#### **Results – Total Coverage**

The 3D Photogrammetric and Classification approaches accurately extracted depths up to 15 m



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# The International Hydrographic Organization (IHO) S-57 Standard

CATZOC Level	Depth Range (m)	Required Accuracy (± m)
A 1	0-10	0.6
Al	10-30	0.8
	0-10	1.2
A2 & B	10-30	1.6
0	0-10	2.5
C	10-30	3.5





#### **Accuracy Assessment for individual SDB techniques**

#### Results for individual SDB techniques in the common coverage area

SDB Method	LE90 (m) Depth Range								
	Bias (0–10 m)	0–10	0–2	2–4	4–6	6–8	8–10	10–14	
Empirical	-0.20	0.95	1.51	1.14	0.75	1.02	0.93	1.46	
Manual Photogrammetry	-0.58	1.58	1.51	1.68	1.35	1.38	1.19	1.76	
Automatic Photogrammetry	0.75	1.54	0.46	0.65	1.45	1.55	1.88	2.10	
Random Forest	-0.38	1.67	0.48	0.54	1.08	1.73	2.28	2.76	
Number of Points	38,773		765	2128	13,511	18,168	4201	359	

Empirical approach very close to meet the CATZOC A2 & B , 1.2 m





# **Dark Features (Benthic Environment)**

Dark features, commonly caused by underwater vegetation, are of particular concern for the empirical approach as it confuses dark features with deep water





#### **Homogeneous Bottom Types**

**Homogenous areas :** For the **Photogrammetric Automatic approach**, within homogeneous areas **like sand**, the algorithm encounters difficulties with matching pixels, preventing a correlation from being achieved









## Level of Confidence Approach

- The percentage of the overlap area captured by four, three and two agreeing techniques that agree within 1 m
- 81 % of the total common coverage agreed with at least 3 techniques

Number of Techniques Agreeing within 1 m	Approaches within Combination <sup>1</sup>	Overall Combination RMSE (m) (0–10 m)	Rank	% Coverage of Overlap Area <sup>2</sup>
4	AP, EM, MP, RF	0.61	1	31
	AP, EM, RF	0.60	2	
3	AP, MP, RF	0.64	3	FO
	AP, EM, MP	0.69	4	50
	EM, MP, RF	0.80	5	
	AP, EM	0.63	6	
	AP, RF	0.70	7	
2	AP, MP	0.71	8	10
	EM, MP	0.82	9	15
	EM, RF	0.83	10	
	MP, RF	0.90	11	





#### **Results of Level of Confidence Approach**

Number of			LE90 (m)							
Techniques				Depth Range						
Agreeing within 1 m	Coverage %	Bias	0–10	0–2	2–4	4–6	6–8	8–10	10–14	
4	31	-0.10	1.01	1.21	0.85	0.85	0.98	1.27	1.00	
3	50	-0.19	1.26	1.23	0.90	1.14	1.28	1.25	1.24	
2	19	0.05	1.28	1.30	1.21	1.25	1.24	1.07	1.90	
4 and 3	81	-0.16	1.21	1.26	0.87	1.08	1.24	1.28	1.20	
All	100	-0.12	1.24	1.30	0.95	1.15	1.24	1.18	1.78	



#### **Individual approaches**

SDB Method	LE90 (m) Depth Range							
	Bias	0–10	0–2	2–4	4–6	6–8	8–10	10–14
Empirical	-0.20	0.95	1.51	1.14	0.75	1.02	0.93	1.46
Manual Photogrammetry	-0.58	1.58	1.51	1.68	1.35	1.38	1.19	1.76
Automatic Photogrammetry	0.75	1.54	0.46	0.65	1.45	1.55	1.88	2.10
Random Forest	-0.38	1.67	0.48	0.54	1.08	1.73	2.28	2.76

Bias was reduced

#### CATZOC B until 14 m for 81 % of the total coverage

#### Level of confidence approach ↓

Number of				LE90 (m)					
Techniques				Depth Range					
Agreeing within 1 m	Coverage %	Bias	0–10	0–2	2–4	4–6	6–8	8–10	10–14
4	31	-0.10	1.01	1.21	0.85	0.85	0.98	1.27	1.00
3	50	-0.19	1.26	1.23	0.90	1.14	1.28	1.25	1.24
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4 and 3	81	-0.16	1.21	1.26	0.87	1.08	1.24	1.28	1.20 <
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#### **SDB Confidence Level masks**











#### **Source Classification Diagram**



# CHS released its first chart (4955) with mention of SDB as a source





14.

# Conclusion



- The 3D manual photogrammetric extraction was the approach that provided the most SDB coverage but is more time intensive and costly
- The empirical approach provided the best overall accuracy but is sensitive to dark features
- The photogrammetric automatic approach is not affected by dark features but its coverage is limited
- The classification provided good results until 15 m of water depth and is less sensitive to dark feature than the empirical approach

For CHS, the best approach would be a hybrid approach that would use the advantages of the different approaches. The **Level of Confidence Approach** provides an automated way of reducing the weakness of the individual approach and increases the accuracy and stability of the SDB model

#### Other advantages of the Level of Confidence approach are :

- •Creation of a mask (reduce time of QC to focus on the problematic areas),
- •Classification in different CATZOC categories (B & C),
- •Increases the confidence in the results (Reduce the SDB uncertainty)



#### **SDB Sensor Selection**



WorldView-2 / 2 m LE90: 0.88 m



Pléiades / 2 m LE90: 1.00 m



PlanetScope / 3 m LE90: 1.32 m



Landsat-8 / 30 m LE90: 2.04 m Canada



SPOT / 6 m LE90: 1.30 m



Sentinel-2 / 10 m LE90: 1.86 m





#### **SDB Sensor Accuracy**







# Questions?

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